

# PROJECTED WALLPAPER PATTERNS

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ABSTRACT. Consider a periodic function  $f$  of two variables with symmetry  $\Gamma$  and let  $\mathcal{L} \subset \Gamma$  be the subgroup of translations. The Fourier expansion of a periodic function is a sum over  $\mathcal{L}^*$ , the dual of the set  $\mathcal{L}$  of all the periods of  $f$ . After projecting  $f$ , some of its original symmetry remains. We describe the symmetries of the projected function, starting from  $\Gamma$  and from the structure of  $\mathcal{L}^*$ .

## 1. INTRODUCTION AND PRELIMINARIES

An usual method of studying bifurcation [5] on problems equivariant under the Euclidean group  $\mathbf{E}(2)$  is to look for periodic solutions — see [2, 3, 4]. If  $f : \mathbf{R}^2 \rightarrow \mathbf{R}$  has two noncolinear periods then its symmetry group is a plane crystallographic group,  $\Gamma \leq \mathbf{E}(2)$ , and its level sets form a periodic pattern.

We start with a pattern in  $\mathbf{R}^2$  and project it into  $\mathbf{R}$ . What are the symmetries of the projected pattern? This question is addressed in [6]. The new pattern, the level sets of a function in  $\mathbf{R}$ , may be periodic or invariant under reflections. We relate the existence of these symmetries to properties of  $\Gamma$  and of  $\mathcal{L}^*$ , the dual of the set  $\mathcal{L}$  of all the periods of  $f$ . The set  $\mathcal{L}^*$  arises naturally in the Fourier expansion of  $f$  and the symmetries in  $\Gamma$  impose restrictions on Fourier coefficients.

We write elements of  $\mathbf{E}(2) = \mathbf{R}^2 \dot{+} \mathbf{O}(2)$  in the form  $(v_\delta, \delta)$ , with  $v_\delta \in \mathbf{R}^2$  representing a translation and  $\delta \in \mathbf{O}(2)$ . They act in  $f : \mathbf{R}^2 \rightarrow \mathbf{R}$  with the scalar action (see [7]):

$$(v_\delta, \delta) \cdot f(x) = f((v_\delta, \delta)^{-1} \cdot x) = f(\delta^{-1}x - \delta^{-1}v_\delta).$$

We assume that  $\Gamma$  is a plane crystallographic group — see [1, 8] for general results and definitions. Denote by  $\mathcal{L}$  the subgroup of the translations in  $\Gamma$ , a module over the integers, also called a lattice. If  $f$  is  $\Gamma$ -invariant, then in particular elements of  $\mathcal{L}$  are periods of  $f$ . A pattern and the lattice  $\mathcal{L}$  may not have the same symmetries: see figure 1.

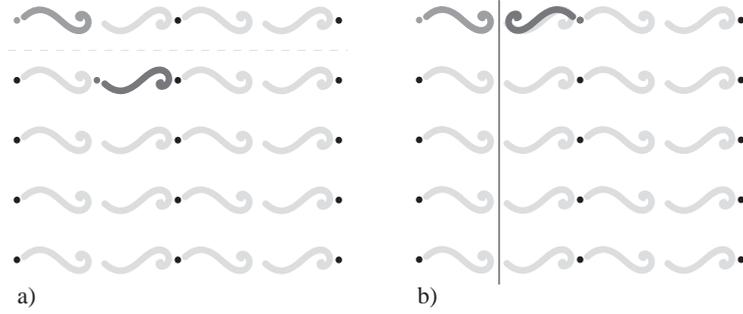


FIGURE 1. a) The lattice (black dots) is not invariant under the glide reflection transforming the grey motive into the darker one. However this is a symmetry of the lighter pattern. b) The lighter pattern is not invariant under the reflection on the black line, although this is a symmetry of the lattice (black dots).

## 2. SYMMETRIES AND PROJECTION

Let  $X_\Gamma$  be a vector space of  $\Gamma$ -invariant functions  $f : \mathbf{R}^2 \rightarrow \mathbf{R}$ , having unique formal Fourier expansions of the form:

$$f(x, y) = \sum_{k \in \mathcal{L}^*} \omega_k(x, y) C(k),$$

where  $\mathcal{L}^*$  is the dual lattice and  $\omega_k(x, y) = e^{2\pi i \langle k, (x, y) \rangle}$ .

The elements of  $\mathcal{L}^*$  are  $k \in \mathbf{R}^2$  such that  $\langle k, l \rangle \in \mathbf{Z}$  for all  $l \in \mathcal{L}$ , where  $\langle k, l \rangle$  is the usual inner product in  $\mathbf{R}^2$ .

Given  $y_0 > 0$ , define the projection of a function  $f \in X_\Gamma$  to be the function

$$\Pi_{y_0}(f)(x) = \int_0^{y_0} f(x, y) dy \quad x, y \in \mathbf{R}.$$

We assume that in  $X_\Gamma$  we have,

$$\Pi_{y_0}(f)(x) = \sum_{k \in \mathcal{L}^*} \int_0^{y_0} \omega_k(x, y) C(k) dy$$

and that  $X_\Gamma$  contains, for all  $k \in \mathcal{L}^*$ , the real and imaginary parts of  $I_k(x, y) = \sum_{\delta \in \mathbf{J}} \omega_{\delta k}(-v_\delta) \omega_{\delta k}(x, y)$ , where  $\mathbf{J} \sim \Gamma/\mathcal{L}$  is the largest subgroup of  $\mathbf{O}(2)$  that leaves  $\mathcal{L}$  invariant. Notice that these are the simplest  $\Gamma$ -invariant functions.

The first step in obtaining the symmetries of the projected functions is to relate the  $(v_\alpha, \alpha)$ -invariance to restrictions on  $\Gamma$  and on  $\mathcal{L}^*$ . This is the main result in this paper: Proposition 2.1, below.

For  $\alpha \in \{1, -1\}$ , let  $\alpha_+ \in \{I, -\sigma\}$  and  $\alpha_- = \sigma\alpha_+ \in \{\sigma, -I\}$ , where

$$\alpha_+ = \begin{pmatrix} \alpha & 0 \\ 0 & 1 \end{pmatrix} \quad \text{and} \quad \sigma = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}.$$

Note that  $\alpha_\pm = \alpha_\pm^{-1}$  and  $\sigma = \sigma^{-1}$ .

**Proposition 2.1.** *All functions in  $\Pi_{y_0}(X_\Gamma)$  are invariant under the action of  $(v_\alpha, \alpha) \in \mathbf{R} \dot{+} \mathbf{O}(1)$  if and only if one of the following conditions holds:*

- A.  $(v_+, \alpha_+) \in \Gamma$  and for each  $k \in \mathcal{L}^*$ , either  $\langle k, (0, y_0) \rangle \in \mathbf{Z} - \{0\}$  or  $\langle k, v_+ - (v_\alpha, 0) \rangle \in \mathbf{Z}$ ,
- B.  $(v_-, \alpha_-) \in \Gamma$  and for each  $k \in \mathcal{L}^*$ , either  $\langle k, (0, y_0) \rangle \in \mathbf{Z} - \{0\}$  or  $\langle k, v_- - (v_\alpha, y_0) \rangle \in \mathbf{Z}$ ,
- C.  $(v_\sigma, \sigma), (v_+, \alpha_+) \in \Gamma$  and, for each  $k \in \mathcal{L}^*$ , one of the conditions C1, C2 or C3 below holds:
  - C1.  $\langle k, (0, y_0) \rangle \in \mathbf{Z} - \{0\}$ ,
  - C2.  $\langle k, v_+ - (v_\alpha, 0) \rangle \in \mathbf{Z}$ ,
  - C3.  $\langle k, v_\sigma - (0, y_0) \rangle + \frac{1}{2} \in \mathbf{Z}$ .

A more concise formulation of this result is possible using the subsets of  $\mathcal{L}^*$  defined below. Let  $\mathcal{M}_+^*$  and  $\mathcal{M}_-^*$  be the modules

$$\begin{aligned} \mathcal{M}_+^* &= \{k \in \mathcal{L}^* : \langle k, v_+ - (v_\alpha, 0) \rangle \in \mathbf{Z}\} \text{ and} \\ \mathcal{M}_-^* &= \{k \in \mathcal{L}^* : \langle k, v_- - (v_\alpha, y_0) \rangle \in \mathbf{Z}\}, \end{aligned}$$

and let

$$\begin{aligned} \mathcal{N}_{y_0}^* &= \{k \in \mathcal{L}^* : \langle k, (0, y_0) \rangle \in \mathbf{Z} - \{0\}\}, \\ \mathcal{N}_\sigma^* &= \{k \in \mathcal{L}^* : \langle k, v_\sigma - (0, y_0) \rangle + 1/2 \in \mathbf{Z}\}. \end{aligned}$$

The last two sets are not modules. The smallest modules generated by each of them are, respectively,  $\overline{\mathcal{N}}_{y_0}^* = \mathcal{N}_{y_0}^* \cup \mathcal{M}_{y_0}^*$  and  $\overline{\mathcal{N}}_\sigma^* = \mathcal{N}_\sigma^* \cup \mathcal{M}_\sigma^*$ , where all the unions are disjoint and  $\mathcal{M}_{y_0}^*$  and  $\mathcal{M}_\sigma^*$  are the modules

$$\begin{aligned} \mathcal{M}_{y_0}^* &= \{k \in \mathcal{L}^* : \langle k, (0, y_0) \rangle = 0\} \text{ and} \\ \mathcal{M}_\sigma^* &= \{k \in \mathcal{L}^* : \langle k, v_\sigma - (0, y_0) \rangle \in \mathbf{Z}\}. \end{aligned}$$

**Properties of  $\mathcal{N}_\sigma^*$ :** Let  $m_1, m_2 \in \mathbf{Z}$ . If  $g_1, g_2 \in \mathcal{N}_\sigma^*$  then

$$(1) \quad m_1 g_1 + m_2 g_2 \in \begin{cases} \mathcal{M}_\sigma^* & \text{if } m_1 + m_2 \text{ even} \\ \mathcal{N}_\sigma^* & \text{if } m_1 + m_2 \text{ odd} \end{cases}.$$

Proposition 2.1 can therefore be written the following way:

**Proposition 2.2.** *All functions in  $\Pi_{y_0}(X_\Gamma)$  are invariant under the action of  $(v_\alpha, \alpha) \in \mathbf{R} \dot{+} \mathbf{O}(1)$  if and only if one of the following conditions holds:*

- A.  $(v_+, \alpha_+) \in \Gamma$  and  $\mathcal{L}^* = \mathcal{N}_{y_0}^* \cup \mathcal{M}_+^*$ ,
- B.  $(v_-, \alpha_-) \in \Gamma$  and  $\mathcal{L}^* = \mathcal{N}_{y_0}^* \cup \mathcal{M}_-^*$ ,
- C.  $(v_\sigma, \sigma), (v_+, \alpha_+) \in \Gamma$  and  $\mathcal{L}^* = \mathcal{N}_{y_0}^* \cup \mathcal{M}_+^* \cup \mathcal{N}_\sigma^*$ .

For  $D(k_1) = \sum_{k_2: (k_1, k_2) \in \mathcal{L}^*} C(k_1, k_2) \int_0^{y_0} \omega_{k_2}(y) dy$ , the projection of  $f \in X_\Gamma$  may be written, with  $\mathcal{L}_1^* = \{k_1 : (k_1, k_2) \in \mathcal{L}^*\}$ , as

$$\Pi_{y_0}(f)(x) = \sum_{k_1 \in \mathcal{L}_1^*} \omega_{k_1}(x) D(k_1).$$

Thus  $\Pi_{y_0}(f)$  is  $(v_\alpha, \alpha)$ -invariant if and only if

$$(2) \quad \sum_{k_1 \in \mathcal{L}_1^*} \omega_{k_1}(x) D(k_1) = \sum_{k_1 \in \mathcal{L}_1^*} \omega_{k_1}(\alpha x) \omega_{k_1}(-\alpha v_\alpha) D(k_1),$$

or, equivalently,  $D(k_1) = \omega_{k_1}(-v_\alpha) D(\alpha k_1)$ , for all  $k_1 \in \mathcal{L}_1^*$ .

In the next section we show that each condition of Proposition 2.1 leads to the restrictions on the coefficients  $D(k_1)$  above. Reciprocally, when those restrictions are imposed on the projection of  $I_k(x, y)$ , for all  $k \in \mathcal{L}^*$ , this implies the conditions of Proposition 2.1.

### 3. PROOF OF PROPOSITION 2.2

Let  $f \in X_\Gamma$  and  $(v_\alpha, \alpha) \in \mathbf{R} \dot{+} \mathbf{O}(1)$ . If  $\Pi_{y_0}(f)$  is  $(v_\alpha, \alpha)$ -invariant then  $\Pi_{y_0}(f)(x) = \Pi_{y_0}(f)(\alpha x - \alpha v_\alpha)$ , which is equivalent to (2). The right hand side of (2) equals  $\sum_{k_1 \in \mathcal{L}_1^*} \omega_{\alpha k_1}(x) \omega_{\alpha k_1}(v_\alpha) D(k_1)$ . Since  $\alpha(\mathcal{L}_1^*) = (\mathcal{L}_1^*)$  and Fourier expansions are unique, then for each  $k_1 \in \mathcal{L}_1^*$ , we have:

$$(3) \quad D(k_1) - \omega_{k_1}(-v_\alpha) D(\alpha k_1) = 0.$$

*Proof — sufficiency.* The difference in (3) may be written as

$$(4) \quad \sum_{k_2: (k_1, k_2) \in \mathcal{L}^*} C(k_1, k_2) G(k_1, k_2) \int_0^{y_0} \omega_{k_2}(y) dy.$$

In each case we compute  $G(k_1, k_2)$  and use the conditions on  $\mathcal{L}^*$ .

Suppose  $\alpha_+ \in \mathbf{J}$ . Then all the Fourier coefficients of any  $f \in X_\Gamma$  satisfy  $C(k) = \omega_k(-v_+) C(\alpha k)$  and  $G(k_1, k_2) = 1 - \omega_k(v_+ - (v_\alpha, 0))$ . Thus  $G(k_1, k_2) = 0$  if  $\langle k, v_+ - (v_\alpha, 0) \rangle \in \mathbf{Z}$ .

If  $(v_-, \alpha_-) \in \Gamma$  then  $G(k_1, k_2) = 1 - \omega_k(v_- - (v_\alpha, y_0))$ , since

$$(5) \quad \int_0^{y_0} \omega_{-k_2}(y) dy = \omega_{k_2}(-y_0) \int_0^{y_0} \omega_{k_2}(y) dy.$$

Then  $G(k_1, k_2) = 0$  if  $\langle k, v_- - (v_\alpha, y_0) \rangle \in \mathbf{Z}$ .

When both  $(v_+, \alpha_+)$  and  $(v_-, \alpha_-)$  lie in  $\Gamma$  then

$$G(k_1, k_2) = 1 + \omega_k(v_\sigma) \omega_{k_2}(-y_0) - \omega_{k_1}(-v_\alpha) (\omega_k(v_+) + \omega_k(v_-) \omega_{k_2}(-y_0)).$$

Using  $\omega_k(v_-) = \omega_k(v_\sigma) \omega_k(\sigma v_+)$  and  $\omega_k(\sigma v_+ - v_+) = 1$  we get

$$G(k_1, k_2) = (1 - \omega_k(v_+ - (v_\alpha, 0))) (1 + \omega_k(v_\sigma - (0, y_0))).$$

If either  $1 - \omega_k(v_+ - (v_\alpha, 0)) = 0$  or  $1 + \omega_k(v_\sigma - (0, y_0)) = 0$  then  $G(k_1, k_2) = 0$ .

It follows from the conditions on  $\mathcal{L}^*$  that for each  $k \in \mathcal{L}^*$  either  $\int_0^{y_0} \omega_{k_2}(y) dy = 0$  or  $G(k_1, k_2) = 0$  and thus (3) holds for all  $k \in \mathcal{L}^*$ .  $\square$

*Proof — necessity.* For  $D'(\delta, k) = \omega_{\delta k}(-v_\delta) \int_0^{y_0} \omega_{\delta k|_2}(y) dy$ , the projections of  $I_k$ , with  $k \in \mathcal{L}^*$ , are

$$\Pi_{y_0}(I_k)(x) = \sum_{\tilde{k}_1 \in \mathbf{J}k|_1} \omega_{\tilde{k}_1}(x) \sum_{\tilde{k}_2: (\tilde{k}_1, \tilde{k}_2) \in \mathbf{J}k} D'(\delta, \tilde{k}),$$

where  $\delta k|_j$  denotes the  $j^{\text{th}}$  coordinate of  $\delta k$ . If  $\Pi_{y_0}(I_k)$  is  $(v_\alpha, \alpha)$ -invariant then, by (3),

$$\sum_{\delta \in J^I(k)} D'(\delta, k) - \omega_{k_1}(-v_\alpha) \sum_{\delta \in J^\alpha(k)} D'(\delta, k) = 0,$$

where  $J^I(k) = \{\delta \in \mathbf{J} : \delta k|_1 = k_1\}$  and  $J^\alpha(k) = \{\delta \in \mathbf{J} : \delta k|_1 = \alpha k_1\}$ . Let  $\mathbf{J}^I = \{I, \sigma\} \cap \mathbf{J}$  and  $\mathbf{J}^\alpha = \{\alpha_+, \alpha_-\} \cap \mathbf{J}$ . We list some properties of  $J^I(k)$  and  $J^\alpha(k)$  in Lemma 3.1 below. Then we describe the set  $\mathcal{O}^* = \{k \in \mathcal{L}^* : J^I(k) = \mathbf{J}^I \wedge J^\alpha(k) = \mathbf{J}^\alpha\}$  in Lemma 3.2. A geometrical characterization of the complement of  $\mathcal{O}^*$  in  $\mathcal{L}^*$  is given in Lemma 3.3 and in Lemma 3.4 we reformulate the cases of Lemma 3.2 in terms of  $\mathcal{L}^*$  instead of  $\mathcal{O}^*$ , completing the proof.  $\square$

**Lemma 3.1.** *For  $k \in \mathcal{L}^*$ , the sets  $J^I(k)$  and  $J^\alpha(k)$  satisfy:*

1.  $J^I(k) = \{\delta \in \mathbf{J} : \delta k = k \vee \delta k = \sigma k\}$ .
2.  $J^\alpha(k) = \{\delta \in \mathbf{J} : \delta k = \alpha_+ k \vee \delta k = \alpha_- k\}$ .
3.  $\mathbf{J}^I \subset J^I(k)$ ,  $\mathbf{J}^\alpha \subset J^\alpha(k)$  and  $J^I(0, 0) = J^\alpha(0, 0) = \mathbf{J}$ .
4. Let  $k = (k_1, k_2) \neq (0, 0)$ . If  $\delta \in J^I(k) - \mathbf{J}^I$  then  $\delta k = (k_1, -|\delta|k_2)$  and if  $\delta \in J^\alpha(k) - \mathbf{J}^\alpha$  then  $\delta k = \alpha(k_1, -|\delta|k_2)$ , where  $|\cdot|$  is the determinant.

*Proof.* Properties 1. and 2. follow by orthogonality of  $\mathbf{J}$  and Property 3. is imediate from this and the definitions.

For property 4, let  $\delta \in J^I(k) - \mathbf{J}^I$  and  $k \neq (0, 0)$ . If  $\delta k = k$  then  $|\delta| = -1$ , since an element of  $\mathbf{O}(2)$  with determinant 1, other than the identity, does not fix any point besides the origin. Similarly if  $\delta k = \sigma k$  then  $|\sigma\delta| = -1$  and  $|\delta| = 1$ . Now suppose  $\delta \in J^\alpha(k) - \mathbf{J}^\alpha$  and  $k \neq (0, 0)$ . Thus, either  $\alpha_+\delta = k$  or  $\alpha_+\delta = \sigma k$ . As  $\alpha_+\delta \in J^I(k) - \mathbf{J}^I$ , we may apply the previous result to  $\alpha_+\delta$ , and the property follows.  $\square$

**Lemma 3.2.** *Suppose that  $\sum_{\delta \in J^I(k)} D'(\delta, k) = \omega_{k_1}(-v_\alpha) \sum_{\delta \in J^\alpha(k)} D'(\delta, k)$  for all  $k = (k_1, k_2) \in \mathcal{L}^*$ . Then one of the following cases holds:*

1.  $\mathbf{J}^I = \{I\}$ ,  $\mathbf{J}^\alpha = \emptyset$  and  $\mathcal{O}^* \subset \mathcal{N}_{y_0}^*$ ,
2.  $\mathbf{J}^I = \{I, \sigma\}$ ,  $\mathbf{J}^\alpha = \emptyset$  and  $\mathcal{O}^* \subset (\mathcal{N}_{y_0}^* \cup \mathcal{N}_\sigma^*)$ ,
3.  $\mathbf{J}^I = \{I\}$ ,  $\mathbf{J}^\alpha = \{\alpha_+\}$  and  $\mathcal{O}^* \subset (\mathcal{N}_{y_0}^* \cup \mathcal{M}_+^*)$ ,
4.  $\mathbf{J}^I = \{I\}$ ,  $\mathbf{J}^\alpha = \{\alpha_-\}$  and  $\mathcal{O}^* \subset (\mathcal{N}_{y_0}^* \cup \mathcal{M}_-^*)$ ,
5.  $\mathbf{J}^I = \{I, \sigma\}$ ,  $\mathbf{J}^\alpha = \{\alpha_+, \alpha_-\}$  and  $\mathcal{O}^* \subset (\mathcal{N}_{y_0}^* \cup \mathcal{M}_+^* \cup \mathcal{N}_\sigma^*)$ .

*Proof.* If  $\mathbf{J}^\alpha = \emptyset$  and  $k \in \mathcal{O}^*$  then by hypothesis  $\sum_{\delta \in \mathbf{J}^I} D'(\delta, k) = 0$ . By (5), if  $\sigma \in \mathbf{J}$  then  $(1 + \omega_k(v_\sigma - (0, y_0))) \int_0^{y_0} \omega_{k_2}(y) dy = 0$  and  $\int_0^{y_0} \omega_{k_2}(y) dy = 0$  if  $\sigma \notin \mathbf{J}$ . Cases 1 and 2 follow because  $\int_0^{y_0} \omega_{k_2}(y) dy = 0$  implies  $k \in \mathcal{N}_{y_0}^*$  and  $1 + \omega_k(v_\sigma - (0, y_0)) = 0$  implies  $k \in \mathcal{N}_\sigma^*$ .

In case 3 we have  $(1 - \omega_{k_1}(-v_\alpha)\omega_k(v_+)) \int_0^{y_0} \omega_{k_2}(y) dy = 0$  and the result follows because  $1 - \omega_{k_1}(-v_\alpha)\omega_k(v_+) = 0$  implies  $k \in \mathcal{M}_+^*$ .

In case 4,  $(1 - \omega_{k_1}(-v_\alpha)\omega_k(v_-)\omega_{k_2}(-y_0)) \int_0^{y_0} \omega_{k_2}(y) dy = 0$  and either  $k \in \mathcal{N}_{y_0}^*$  or  $1 - \omega_{k_1}(-v_\alpha)\omega_k(v_-)\omega_{k_2}(-y_0) = 0$ , which implies  $k \in \mathcal{M}_-^*$ .

The hypothesis in case 5 yields  $G(k_1, k_2) \int_0^{y_0} \omega_{k_2}(y) dy = 0$ , where  $G(k_1, k_2) = 1 + \omega_k(v_\sigma) \omega_{k_2}(-y_0) - \omega_{k_1}(-v_\alpha) (\omega_k(v_+) + \omega_k(v_-) \omega_{k_2}(-y_0))$ , as in the proof of sufficiency in Proposition 2.1. Therefore, either  $k \in \mathcal{N}_{y_0}^*$  or  $G(k_1, k_2) = 0$ . In the second case either  $(1 - \omega_k(v_+ - (v_\alpha, 0))) = 0$  or  $(1 + \omega_k(v_\sigma - (0, y_0))) = 0$  and the result follows.  $\square$

Let  $\mathcal{P}^* = \{k \in \mathcal{L}^* : J^I(k) \neq \mathbf{J}^I \vee J^\alpha(k) \neq \mathbf{J}^\alpha\}$  be the complement of  $\mathcal{O}^*$  in  $\mathcal{L}^*$ .

**Lemma 3.3.**  $\mathcal{P}^*$  lies in a finite union of lines through the origin.

*Proof.*  $\mathcal{P}^*$  may be written as a finite union of submodules

$$\mathcal{P}^* = \bigcup_{\delta \in \mathbf{J} - \mathbf{J}^I} \mathcal{M}_{\delta, I}^* \cup \bigcup_{\delta \in \mathbf{J} - \mathbf{J}^\alpha} \mathcal{M}_{\delta, \alpha}^*$$

for  $\mathcal{M}_{\delta, \xi}^* = \{k \in \mathcal{L}^* : \delta k = \xi(k_1, -|\delta|k_2)\}$  and  $\xi = I, \alpha$ . If  $\delta$  is a rotation then for  $k \in \mathcal{M}_{\delta, \xi}^*$  we have  $\delta k = \pm(k_1, -k_2)$ , i.e.,  $k$  lies on the line fixed by  $\pm\sigma\delta$ . Therefore  $\mathcal{M}_{\delta, \xi}^*$  is the intersection of those lines with  $\mathcal{L}^*$ . Similarly, if  $\delta$  is a reflection then  $\mathcal{M}_{\delta, \xi}^*$  is the intersection of  $\mathcal{L}^*$  with a line fixed either by  $\delta$  or by  $-\delta$ .  $\square$

**Lemma 3.4.** If  $\sum_{\delta \in J^I(k)} D'(\delta, k) = \omega_{k_1}(-v_\alpha) \sum_{\delta \in J^\alpha(k)} D'(\delta, k)$  for all  $k = (k_1, k_2) \in \mathcal{L}^*$ , then one of the following cases holds:

- A.  $\mathbf{J}^\alpha = \{\alpha_+\}$  and  $\mathcal{L}^* = \mathcal{N}_{y_0}^* \cup \mathcal{M}_+^*$ ,
- B.  $\mathbf{J}^\alpha = \{\alpha_-\}$  and  $\mathcal{L}^* = \mathcal{N}_{y_0}^* \cup \mathcal{M}_-^*$ ,
- C.  $\mathbf{J}^\alpha = \{\alpha_+, \alpha_-\}$  and  $\mathcal{L}^* = \mathcal{N}_{y_0}^* \cup \mathcal{M}_+^* \cup \mathcal{N}_\sigma^*$ .

*Proof.* Let  $k \in \mathcal{L}^* - \{(0, 0)\}$  and observe that

$$(6) \quad (\mathcal{M}_{y_0}^* \cap \mathcal{P}^*) - \{(0, 0)\} = \emptyset.$$

Let  $g = (1/n)k \in \mathcal{L}^*$ ,  $n \in \mathbf{Z}$ , have minimal norm and choose  $h \in \mathcal{L}^*$  such that  $\mathcal{L}^* = \{g, h\}_{\mathbf{Z}}$ . Let  $\mathcal{Q}_k^* = \{k + mh : m \in \mathbf{Z}\}$ . Since  $\mathcal{Q}_k^*$  is contained in a line in  $\mathbf{R}^2$  that does not go through the origin, by Lemma 3.3, the set  $\mathcal{Q}_k^* \cap \mathcal{P}^*$  is finite.

For  $k \in \mathcal{L}^* - \{(0, 0)\}$  there are three possibilities for  $\mathcal{Q}_k^* \cap \overline{\mathcal{N}_{y_0}^*}$ : it is either the empty set, or a set with only a point, or an infinite set of equally spaced points. This happens because  $\overline{\mathcal{N}_{y_0}^*}$  is a module and if  $k + m_1h \neq k + m_2h \in \mathcal{Q}_k^* \cap \overline{\mathcal{N}_{y_0}^*}$ , then  $(m_2 - m_1)h \in \overline{\mathcal{N}_{y_0}^*}$  and  $\{k + m_1h + m(m_2 - m_1)h : m \in \mathbf{Z}\}$  is a subset of  $(\mathcal{Q}_k^* \cap \overline{\mathcal{N}_{y_0}^*})$ . A characteristic period,  $\tau_{y_0}$ , is given by the smallest difference between two elements of  $\mathcal{Q}_k^* \cap \overline{\mathcal{N}_{y_0}^*}$ .

The same three possibilities hold for  $\mathcal{Q}_k^* \cap \mathcal{N}_\sigma^*$ . Although  $\mathcal{N}_\sigma^*$  is not a module, the smallest difference between two elements of  $\mathcal{Q}_k^* \cap \mathcal{N}_\sigma^*$  defines a period  $\tau_\sigma \in \mathcal{M}_\sigma^*$ , by (1). Thus, whenever  $\mathcal{Q}_k^* \cap \mathcal{N}_\sigma^*$  has more than one element, if  $k + m_1h \in \mathcal{N}_\sigma^*$  then  $\{k + m_1h + m\tau_\sigma : m \in \mathbf{Z}\} = \mathcal{Q}_k^* \cap \mathcal{N}_\sigma^*$ .

Repeating the construction for  $\mathcal{Q}_k^* \cap \mathcal{M}_+^*$  and  $\mathcal{Q}_k^* \cap \mathcal{M}_-^*$  we may define characteristic periods  $\tau_+$  and  $\tau_-$ , respectively, when these sets have more than one element.

We complete the proof following the cases of Lemma 3.2.

Case 1). From  $\mathcal{L}^* = \mathcal{N}_{y_0}^* \cup \mathcal{P}^*$ , we get  $\mathcal{M}_{y_0}^* \subset \mathcal{P}^*$  and, by (6),  $\mathcal{M}_{y_0}^* = \{(0, 0)\}$ . Moreover,  $\mathcal{Q}_k^* \cap \mathcal{N}_{y_0}^*$  must be infinite because  $\mathcal{Q}_k^* \cap \mathcal{P}^*$  is finite. Thus, the period  $\tau_{y_0}$  exists and  $\mathcal{Q}_k^* - \overline{\mathcal{N}_{y_0}^*}$  is either empty or infinite. From  $(\mathcal{Q}_k^* - \overline{\mathcal{N}_{y_0}^*}) \subset (\mathcal{Q}_k^* \cap \mathcal{P}^*)$  it follows that  $\mathcal{L}^* = \overline{\mathcal{N}_{y_0}^*}$ . Since  $\sigma \in \mathbf{J}$ , then  $\mathcal{M}_{y_0}^* \neq \{(0, 0)\}$  and so case 1) cannot occur.

Case 2). Here  $\mathcal{L}^* = \mathcal{N}_{y_0}^* \cup \mathcal{N}_\sigma^* \cup \mathcal{P}^*$  which, by (6), implies  $\mathcal{M}_{y_0}^* \subset (\mathcal{N}_\sigma^* \cup \{(0, 0)\})$ . Moreover,  $\mathcal{M}_{y_0}^* \neq \{(0, 0)\}$  since  $\sigma \in \mathbf{J}$ . Suppose  $\tilde{k} \in \mathcal{M}_{y_0}^*$  and  $\tilde{k} \neq (0, 0)$ , then,  $\tilde{k} \in \mathcal{N}_\sigma^*$  and  $2\tilde{k} \in \mathcal{M}_{y_0}^*$ . However,  $2\tilde{k} \notin \mathcal{N}_\sigma^*$ , by (1), and so case 2) is also impossible.

Case 3). We follow the arguments of case 1) using the least common multiple of the existing periods,  $\tau_{y_0}$  or  $\tau_+$ , instead of  $\tau_{y_0}$ . Therefore  $k \in (\mathcal{N}_{y_0}^* \cup \mathcal{M}_+^*)$  and condition A follows because  $(0, 0) \in \mathcal{M}_+^*$ .

Case 4). This is like case 3) with  $\mathcal{M}_-^*$  and  $\tau_-$  instead of  $\mathcal{M}_+^*$  and  $\tau_+$ , yielding condition B.

Case 5). Here  $\mathcal{Q}_k^* - (\mathcal{N}_{y_0}^* \cup \mathcal{M}_+^* \cup \mathcal{N}_\sigma^*) = \emptyset$  because at least one of the periods  $\tau_{y_0}$ ,  $\tau_+$  or  $\tau_\sigma$  exists and condition C follows.  $\square$

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